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Metaheuristic algorithm for optimal allocation of electric vehicles and photovoltaics in distribution grid

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ABSTRACT

Since electric vehicles (EVs) emit less carbon dioxide, their number is rapidly increasing. As the number of EVs grow, these added loads strain the distribution grid, introducing new challenges. Key concerns for network operators include voltage fluctuations and increased power losses. Properly deploying throughout the grid, photovoltaic (PV) systems and electric vehicle charging stations (EVCS) can assist in lowering power losses and improving the bus voltage profile. A MATLAB implementation of the metaheuristic algorithm called Harris Hawk optimization (HHO) algorithm is developed to select the best locations for integrating EVCSs and PVs, with the goals of enhancing the voltage profile and reducing power losses across buses. IEEE 12-bus and 14-bus systems and real-time distribution grid data were used to test the method. For the 26-bus real-time system, the results demonstrated a notable 24% decrease in overall power loss as compared to the base case and improved voltage regulation, as indicated by a lower average voltage deviation index (AVDI) value of 0.0929. A comparative analysis was performed between optimized and random placements of EVCSs and PVs, as well as against the grey wolf optimization (GWO) algorithm. The results provide a framework for implementing solar-powered EV charging infrastructure. This can reduce costs, enhance energy reliability, and contribute to a cleaner environment.

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1. INTRODUCTION

Distribution network becomes overloaded as a result of electric vehicle (EV) loads. An increase in EV loads can overload distribution transformers and feeders, thereby causing instability of the system This will result in increased loss of power and variation in bus voltages in the grid. This can ultimately lead to the tripping of the distribution network. To maintain stability in the grid, electric vehicle charging stations (EVCS) must be positioned in the distribution network as optimally as possible. Distributed generators (DGs) have been traditionally employed by researchers to achieve better voltage regulation at the buses and reduce associated power losses. Therefore, the problem identified is the optimal allocation of EVCS and PVs inside the distribution grid.

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EV users should consider several factors such as, the availability of suitable charging infrastructure, charging time, and, most importantly, the size and location of charging stations (CSs). This is particularly important in urban areas where land costs and location play a significant role. It is also essential that the CS location is both cost-effective and easily accessible. Based on road network and geographic data, this study [1] presents an intelligent algorithm based planning system for EVCS.

A realistic hybrid grid-RES-based EV fast-CS can be analyzed by considering the characteristics of EV demand. This includes modeling factors such as the battery capacity, state of charge (SOC), arrival and departure timings, and the hourly distribution of EVs at the station. In this work [2], a hybrid genetic algorithm in conjunction with pattern search is used to improve the parameters for this precise modelling of EVs. The best place for EVCSs is a crucial factor in effectively serving EV users and maintaining a healthy power system. This study [3], [4] identifies the best locations by considering aspects such as power loss, voltage variation in the distribution network, and the land cost linked to each site in the road network. Inaccurate EVCS predictions will negatively impact the energy grid. To locate the best place for CSs within the grid, the Harris Hawk optimization (HHO) approach has been employed by [4]. The best location and capacity for DGs and PVs are found using the political optimization approach. Comparing the results with other optimization algorithms demonstrates minimized losses and more stable voltage [5].

It is necessary to go thorough research while charging EVs simultaneously in distribution networks in order to identify potential issues such as congestion, increased power losses, and voltage limit violations. To overcome these challenges, an optimal EV charging schedule is essential since it ensures that charging occurs between non-overlapping time slots and avoids overload scenarios that might compromise the distribution networks performance. To address this problem, a mixed-integer quadratic optimization model has been developed, which integrates photovoltaic (PV) system siting into the optimal framework [6].

Numerous advantages provided by DG units are thought to improve power distribution networks' security. However, by making sure that DG units are positioned and sized properly, these advantages may be further enhanced. Conversely, random placement of these units can adversely affect power systems by worsening the voltage profile and potentially increasing power losses. To address this, Jumaa *et al.* [7] utilize an artificial intelligence technique known as particle swarm optimization (PSO) to determine the optimal placement and sizing of DG units, aiming to minimize power losses and improve the voltage profile. PSO and Monte Carlo simulation are presented in this work, which takes in to account many goals [8]. Flattening the load curve is the main objective of peak shaving and valley filling procedures. Positive results are obtained when the suggested approach is used to a traditional system.

To increase the system's dependability, supplementary power resources should be integrated. One approach is to utilize DGs, which provide both reactive and real power according to demand. The optimal incorporation of multiple DGs into the network boosts the system's reliability. The impact on the dependability of the 33-bus and 69-bus distribution systems is then analyzed after the DG units and EV charging loads are integrated optimally [9]. The artificial Hummingbird program is intended to determine the ideal location for wind and PV systems [10]. The placement of PV and EV is found using three metaheuristic methods. This study looks at particle swarm, and African vulture optimization strategies [11]. The aim is to reduce the expense of the system. Results from the simulation, which was performed on a few sample systems, showed reduced peak demand, less losses, and better voltage profiles. Sales of EVs have increased as a result of phase-out of older, petroleum-powered cars. However, as EVs gained popularity, so did the quantity of EV charge stations. The rapid installation of PVs and EVs has resulted in increased power losses. EV load models for power flow analysis may be developed using user-defined models. Through the use of programming using the power system analysis toolbox, a specific model has been developed for EVs designed as compact city cars for urban environments [12].

The optimal buses for PV and EV installation are found using the AI approach [13], [14]. A new method for figuring out the best place and size for EVCS and renewable energy sources using enhanced GA-PSO algorithm is done [15], [16]. In order to determine the highest levels of EV and renewable-based DG penetration that an electric distribution system can support, this work [17] proposes a method from the viewpoint of operator of the distribution system. Batteries can be used to control variations in PV production in order to fulfil energy demand and enhance the sustainability of CSs. A MATLAB simulation of a standalone PV-powered EVCS is shown in this paper [18]. Power quality issues and its mitigations are reviewed in this work [19]. The functionality of distribution grid is compromised by the increasing use of EVs. Consequently, the location of the EVCS affects the DS dependability. The DS's degradation as a result of an improper EVCS position is the main challenge. A novel algorithm is used to determine best location for DSTATCOM and EVCS allocation in DS is discussed [20]. Future research directions must include developing advanced optimization algorithms, exploring the integration of renewable energy sources into the charging infrastructure, investigating the potential of vehicle-to-grid (V2G) services, evaluating how EV charging affects the electrical infrastructure and developing plans for organizing and planning EV charging for sizable fleets [21].

Gaps found in the literature: i) the addition of EV loads increases power losses, but optimal EV placement can reduce these losses compared to random allocation. Scenarios not clearly addressed in existing literature, ii) although the optimal distribution of EVs has been examined, their integration with DGs has not [22], iii) this analysis only included PV CSs, not the combination of EVs and PV [23], iv) the analysis primarily focused on IEEE example systems, which is inadequate, as real-time data and various scenarios were not taken into account [24], and v) not more than 12.08% reduction in power losses was achieved utilizing the grey wolf optimization (GWO) method [25].

Significance of this study considering the limitations of the aforementioned studies, a novel optimization algorithm is proposed. Eight different scenarios involving EVCS and PV integration are analyzed. The key innovation of this paper lies in the application of the HHO algorithm to real-time data from a distribution grid in a small Indian town. Utilizing real-time data from a small town offers precise, location-specific insights that reflect the area's actual conditions and challenges. This improves the reliability of the research findings, ensuring the proposed solutions are both practical and directly applicable. Additionally, it reveals unique patterns and behaviors that might be overlooked in generic or simulated datasets.

This study suggests utilizing the HHO approach to plan an EVCS. The remainder of the paper is structured as follows. Method is in section 2. Results and discussions in section 3. While conclusions in section 4.

2. METHOD

In India, the establishment of EVCS and solar-powered EV charging infrastructure is still at a nascent stage. Solar EVCS are increasingly recognized as a sustainable solution, capitalizing on the country's abundant solar energy resources. However, the overall infrastructure and technology are still evolving, which emphasizes the importance of this study. The systematic approach and techniques employed in this paper are as follows:

- Implementation of HHO algorithm for ideal positioning of PVs and EVs on the IEEE 12 bus, 15 bus example systems.
- The use of real-world data from a distribution grid of a small town in India.
- Comprehensive studies are conducted across various scenarios.
- DGs such as PV generation are included in the analysis.
- Percentage reduction in losses is tabulated and compared with GWO method.
- The HHO algorithm results are compared with other algorithms from the literature and analyzed.

With inspiration from the EVCS planning research publications mentioned above, a novel optimization technique called Harris Hawk is considered to locate optimal places for EVCS in the distribution grid. PV generation is considered as DG sources. The algorithm is initially tested for IEEE-12 and 15 bus systems. By examining a broad range of scenarios, potential risks and vulnerabilities that could arise in real-world usage can be identified. This helps mitigate performance, reliability, and security risks, ensuring the system meets its requirements and performs optimally in various situations.

To validate the proposed HHO algorithm, simulations are conducted also on the real distribution grid data of the Hiremagaluru express feeder in Chikkamagaluru, Karnataka, India.

2.1. Goal function

To increase the distribution network's performance, placement of EVs and PVs in the network is optimized. The goals of the study stabilize the bus voltage and reduce loss in power. The goal function of the system for power losses is given by (1):

$$F_1(n) = MIN \sum_{i=1}^{e} R_i * I_i^2$$
 (1)

where e is the total quantity of elements and i is their number. The resistance of the i^{th} element is Ri and I_i the current in the i^{th} element. Average voltage deviation index (AVDI) is the variation of voltage from 1 pu of reference voltage considered is given by (2):

$$F_2(n) = \frac{1}{b}MIN \sum_{n=1}^{b} |1 - V_n|^2$$
 (2)

where n is the bus number, V_n is the voltage at nth bus, b represents number of buses.

The stability of the system can be determined by looking at the value of VSI that is lowest. In order to lower loss of power, average potential difference deviation, the absolute objective function is created. Mathematically it is represented as (3):

$$F(n) = MIN[W_1F_1(n) + W_2F_2(n)]$$
(3)

weights W₁ and W₂ are assumed equal weights and assumed as (1).

2.2. Constraints

The limitations on the needs for power balance:

$$\sum_{n=1}^{b} PG_n - P_L = P_D \tag{4}$$

$$\sum_{n=1}^{b} QG_n - Q_L = Q_D \tag{5}$$

where P_{L} , Q_{L} , P_{D} , Q_{D} are loads and demands for both real and reactive power respectively.

The highest allowable generated power by DGs must not exceed the acceptable limit of distribution systems. Additionally, voltage deviation must not exceed 5%.

$$PG_n^{Min} \le PG_n \le PG_n^{Max} \tag{6}$$

$$QG_n^{Min} \le QG_n \le QG_n^{Max} \tag{7}$$

$$0.95 \le V_n \le 1.05 \tag{8}$$

PG_n is real power generation and QG_n is reactive power generation at the nth bus.

2.3. Harris Hawk optimization algorithm workflow

The HHO algorithm is developed to achieve the goals while considering the aforementioned constraints. The workflow is displayed in Figure 1.

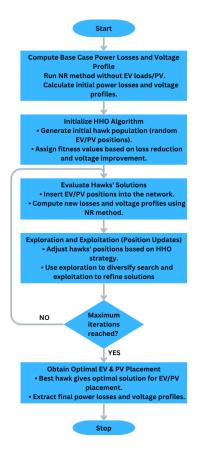


Figure 1. HHO work flow diagram

2.4. Cases under consideration

EVs and PV systems introduce uncertainty due to charging demand variation, solar fluctuations, and grid impacts like voltage stability and power loss. Simulating different scenarios helps analyze grid behavior and optimize EV/PV placement. Hence various cases are taken in to consideration.

Case 1: base case load flow studies without connecting any PVs and EVs. Power losses are lower compared to all other scenarios.

Case 2 : a bus recommended by the HHO algorithm is chosen to connect one EV.

Case 3: buses recommended by the HHO algorithm are chosen to connect two EVs.

Case 4 : buses recommended by the HHO algorithm are chosen to connect three EVs. Each additional EV load increases power losses. Bus voltages to fluctuate.

Case 5: buses recommended by the HHO algorithm are chosen to connect three EVs and three PVs. Power losses will reduce because of PVs. Better Voltage deviation index.

Case 6: three EVs are connected at randomly selected the buses. The increase in power losses is significantly higher compared to the HHO-based optimal location, as seen in Case 4.

3. RESULTS AND DISCUSSION

HHO algorithm was run in MATLAB. The solution in terms of ideal locations is obtained. The analysis assumes a 250-kW CS with 5 connectors for simultaneous charging of five EVs. The potential for a 150-kW solar-powered CS is considered. The convergence curves for IEEE 12-bus, 15-Bus and real time 26-Bus system for cases 1, 3, and 6 are presented accordingly in Figures 2 to 4. Convergence is achieved within 10 iterations when applying the NR method.

From Figure 2(a), it is evident that in the base case load flow study (Case 1) for the IEEE 12-bus system, the solution converged in 4 iterations. The active power loss (Ploss) was found to be 17.2313 kW, and the reactive power loss (Qloss) was 10.2512 kVAr, which are the minimum values due to the absence of additional EV loads. In Figure 2(b), the solution converged in 3 iterations when 3 EVs were connected at optimal bus locations 2 to 4. The corresponding Ploss and Qloss increased to 46.227 kW and 23.7843 kVAr, respectively, indicating that power losses rise with the inclusion of EV loads. Figure 2(c) shows that when the 3 EVs were connected at random bus locations 10, 11, and 12, the solution required 7 iterations to converge. The losses increased significantly, with Ploss reaching 270.117 kW and Qloss rising to 119.28 kVAr, as observed in Case 6.

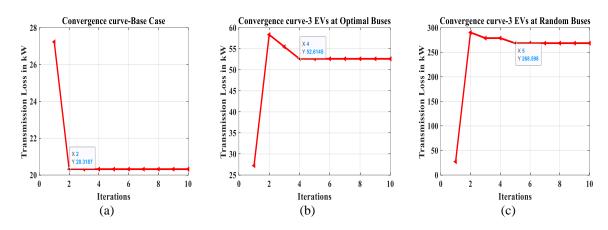


Figure 2. Convergence curves for 12 bus system; (a) base case, (b) 3 EV at optimal buses, and (c) 3 EV at random buses

Moreover, sequentially connecting EVCSs at optimal locations (Cases 2 to 4) results in a gradual increase in both Ploss and Qloss. In contrast, the integration of PV systems (Case 5) results in a minor decrease in power losses.

Comparable results were observed for both the IEEE 15-bus system and the real-time 26-bus system, as illustrated in Figures 3(a)-(c) and 4(a)-(c), respectively. These outcomes highlight the efficiency of the HHO algorithm in substantially minimizing power losses and improving grid stability. A consolidated summary of the results is presented in Table 1.

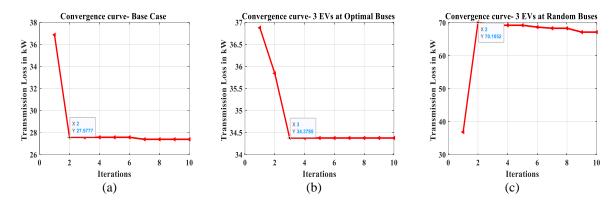


Figure 3. Convergence curves for 15 bus system; (a) base case, (b) 3 EV at optimal buses, and (c) 3 EV at random buses

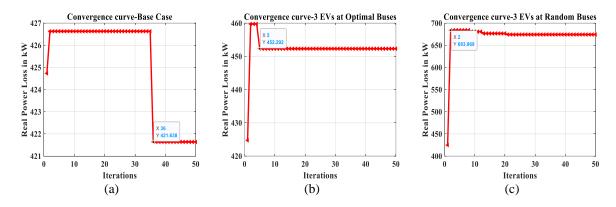


Figure 4. Convergence curves for 26 bus system; (a) base case, (b) 3 EV at optimal buses, and (c) 3 EV at random buses

| Table 1 Actual | l and reactive | loss of nowe | r for differen | t cases |
|----------------|----------------|--------------|----------------|---------|

| 1 doic | 1. 7 ictual alia i | cactive ic | os or pov | ver for ur. | i i ci cii ca | .505 | | | | | | |
|--------------------------|--------------------|------------|-----------|-------------|---------------|---------|---------|--|--|--|--|--|
| T | Nature of loss | Cases | | | | | | | | | | |
| Type of system | Nature of loss | 1 | 2 | 3 | 4 | 5 | 6 | | | | | |
| IEEE 12-bus | Ploss in kW | 17.2313 | 22.453 | 29.827 | 46.227 | 31.2889 | 270.117 | | | | | |
| | Qloss in kVAr | 10.2512 | 12.439 | 18.962 | 23.7843 | 15.3551 | 119.28 | | | | | |
| IEEE 15-bus | Ploss in kW | 26.887 | 34.043 | 33.96 | 34.344 | 27.949 | 55.547 | | | | | |
| | Qloss in kVAr | 63.93 | 71.83 | 72.80 | 69.42 | 61.58 | 90.94 | | | | | |
| Real time data of 26-bus | Ploss in kW | 425.931 | 424.569 | 424.636 | 467.688 | 442.968 | 620.211 | | | | | |
| | Qloss in kVAr | 192.72 | 198.22 | 185.62 | 230.69 | 223.0 | 290.36 | | | | | |

The index representing average voltage deviation known as AVDI, is a measure of deviation of bus voltages from the reference value of 1 pu. Table 2 presents the AVDI values for different scenarios. A lower AVDI signifies smaller voltage fluctuations. For the 26-bus system, the lowest AVDI of 0.0929 is achieved when EVs are allocated to optimal buses 3, 4, and 7, indicating improved voltage stability compared to a higher AVDI of 0.1032 observed with random EV placements at 12, 18, and 25. Similar trends are observed across the IEEE test systems.

Table 2. AVDI for various cases

| Tuble 2: 11 v B1 for various cases | | | | | | | | | | | |
|------------------------------------|-----------|----------------------|---------------------|--|--|--|--|--|--|--|--|
| Type of system | Base case | EVs at optimal buses | EVs at random buses | | | | | | | | |
| 12 bus | 0.0430 | 0.0605 | 0.0979 | | | | | | | | |
| 15 bus | 0.0392 | 0.0588 | 0.0668 | | | | | | | | |
| 26 bus | 0.0863 | 0.0929 | 0.1032 | | | | | | | | |

Percentage reduction in power losses is analyzed for optimal and random EV bus placement. Both HHO and GWO algorithms were employed to identify optimal locations. As shown in Table 3, the proposed HHO

algorithm achieved greater reductions in both Ploss and Qloss compared to the GWO method. The comparison of the proposed HHO algorithm with other algorithms from various literatures is presented in Table 4. It is observed that the HHO method achieves a with a lower AVDI value 0.0605, which indicates reduced voltage fluctuations compared to GWO, PSO, hybrid GWOPSO, African vultures, and salp swarm methods.

Table 3. Comparison of HHO with GWO algorithm for Ploss & Qloss

| Method | % R | eduction in | n P_{loss} | % Reduction in Q _{loss} | | | | |
|--------|--------|-------------|--------------|----------------------------------|--------|--------|--|--|
| Method | 12 bus | 15 bus | 26 bus | 12 bus | 15 bus | 26 bus | | |
| GWO | 74.16 | 32.83 | 17.8 | 73.29 | 19.90 | 16.21 | | |
| HHO | 83.44 | 39.77 | 24.59 | 80.06 | 23.66 | 20.55 | | |

Table 4. Comparison of HHO with other algorithms

| Algorithm | AVDI | References |
|---------------------------------|---------|------------|
| GWO | 0.648 | [9] |
| PSO | 0.6358 | [9] |
| Hybrid GWOPSO | 0.661 | [9] |
| African vultures optimization | 1.99 | [11] |
| Salp swarm | 1.97 | [11] |
| Bacterial foraging optimization | 0.01702 | [26] |
| Hybrid PFOA & PSO | 0.01271 | [26] |
| Proposed HHO | 0.0605 | - |

4. CONCLUSION

The growth of EVCS and solar-powered EV charging infrastructure in India is still in its early phases. As such, this research aims to develop metaheuristic algorithm to identify the best location for EVs and PV systems, which is essential for maintaining the stability of the distribution grid. IEEE 12 and 15 bus distribution networks are two widely recognized IEEE standard example networks on which the suggested HHO method was tested. Later the method is implemented for real time 26 bus power distribution system. It was discovered that the HHO is more efficient compared to GWO method. PVs in the grid will improve voltage levels and reduce power losses. The aforementioned findings support this.

This work provides practical solutions to real-world challenges, benefiting both the academic community and the broader society working towards sustainable energy solutions. The above results offer a data-driven approach to guide policymakers and grid planners in making informed decisions about the design and expansion of EV and PV infrastructure. The proposed bus locations 3, 4, and 7 for EV and PV placement have been suggested to the Mangalore electricity supply company (MESCOM) for consideration in future implementation. Additionally, future research could evaluate the potential cost savings resulting from reduced power losses in the distribution grid.

The transportation industry and the power utility firm should work together to efficiently plan EVCS in order to serve EV consumers. In addition to determining the best locations for EVCS's, this study should eventually examine the daytime fluctuations in PV power production, EV owner's driving habits, unpredictable parameters of distribution network, and times of EV charging in future.

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C: Conceptualization I : Investigation Vi : Visualization M : **M**ethodology R : **R**esources Su: **Su**pervision

So: Software D: Data Curation P: Project administration Va: Validation O: Writing - Original Draft Fu: Funding acquisition

Fo: Formal analysis E: Writing - Review & Editing

CONFLICT OF INTEREST STATEMENT

Authors state no conflict of interest.

DATA AVAILABILITY

Data availability is not applicable to this paper as no new data were created or analyzed in this study.

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